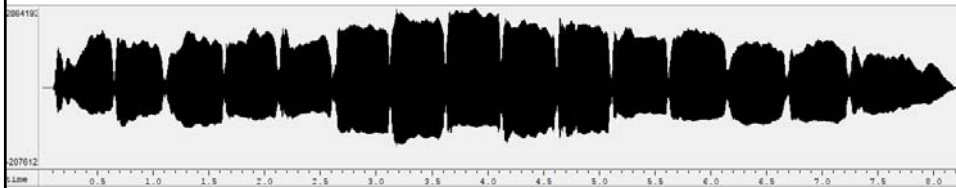


Speech Processing Time-Frequency Representations and dimension reduction

Professor Marie Roch
San Diego State University



What's going on here?



Alternative representations

- Frequency domain: spectrum
- Frequency over time: spectrogram

Frequency domain

- Result of frequency analysis transform
- Discrete Fourier transform (DFT)

$$X(e^{j\omega_0}) = \sum_{k=-\infty}^{\infty} x[k]e^{-j\omega_0 k}$$

- $x[k]$ k^{th} time domain sample
- $X(e^{j\omega_0})$ – content at $\omega_0 = 2\pi \text{ freq}$, e.g. 30 Hz $\omega_0 = 2\pi 30$
- $j = \sqrt{-1}$

DFT

- Euler's formula lets us relate a complex exponential to trigonometric functions

$$Ae^{j\omega n} = A\cos(\omega n) + jA\sin(\omega n)$$

- So for DFT $X(e^{j\omega_0}) = \sum_{k=-\infty}^{\infty} x[k]e^{-j\omega_0 k}$
 - k moves along the unit circle
 - ω_0 controls step speed
 - $\omega_0 = 2\pi * freq$

DFT output

- $X(e^{j\omega_0})$ is a complex value
- The magnitude of the complex value is an indication of pressure strength at a given frequency.
- Squared value is related to intensity

DFT Output

$$\begin{aligned} X(e^{j\omega_0})\overline{X(e^{j\omega_0})} &= (a + bj)(a - bj) \\ &= a^2 - abj + abj + b^2 \\ &= a^2 + b^2 \end{aligned}$$

where \bar{X} , or sometimes X^* ,
denotes the complex conjugate

DFT Output

- Convert to dB rel:

$$\begin{aligned} &10\log_{10}\left(X(e^{j\omega_0})\overline{X(e^{j\omega_0})}\right) \\ \text{or } &20\log_{10}\left(\left|X(e^{j\omega_0})\right|\right) \text{ where } || \text{ is magntiude} \end{aligned}$$

Notes of the Fourier Transform

- The Fourier transform for aperiodic signals exists when:

$$\sum_{n=-\infty}^{\infty} |x[n]| < \infty$$

- It is sometimes convenient to normalize the frequency range to $[-\pi, \pi]$
- To move from a normalized $[-\pi, \pi]$ frequency axis to Hz:

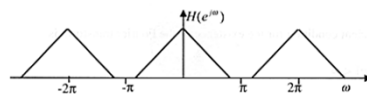


$$f(\omega) = \frac{\omega}{2\pi} \times \text{SamplingRate}, \quad \omega \in [0, 2\pi]$$

9

Notes on the DFT

- The DFT of real signals is periodic with period 2π (normalized frequency axis).



Huang et al. p 209

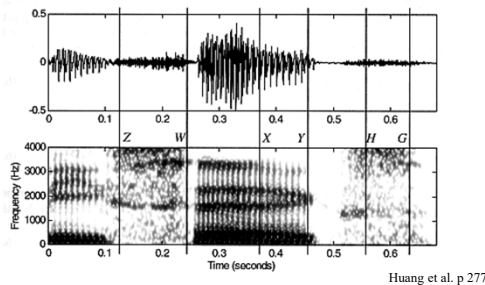
- An alternate form exists for analyzing periodic signals.



10

Short-Time Fourier Analysis

Analyzing the whole signal doesn't make sense, not all regions are similar:

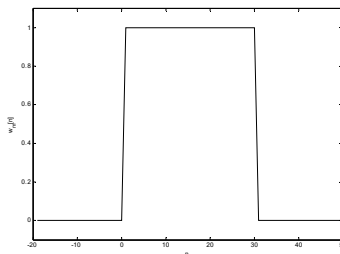


Discrete Frequency & Short-Time Fourier Transforms

- Computational methods require a discrete frequency domain.
- Speech signals change over time and we want to analyze a “static” portion of the signal.

Short-Time Fourier Analysis

- Segment the signal into small *frames* and then perform an analysis on each frame.
- Let $w_m[n]$ be a rectangular window for the m 'th frame.



Short Time Discrete Fourier Transform

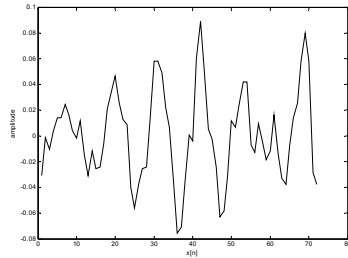
- Assume $x_N[n] = x_N[n+N]$
 - $x_N[n]$ periodic with period N .
- We define the DFT as

$$X_N[k] = \sum_{n=0}^{N-1} x_N[n] e^{-j2\pi nk/N} \text{ where } 0 \leq k < N$$

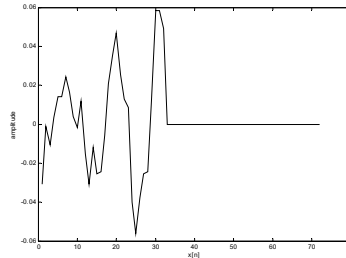
and will refer to this as Fourier analysis

Extracting the short-time signal

- $x[n]$



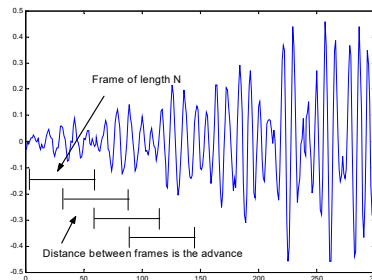
- $x_m[n]=x[n]w_m[n]$



Window function extracts m^{th} frame

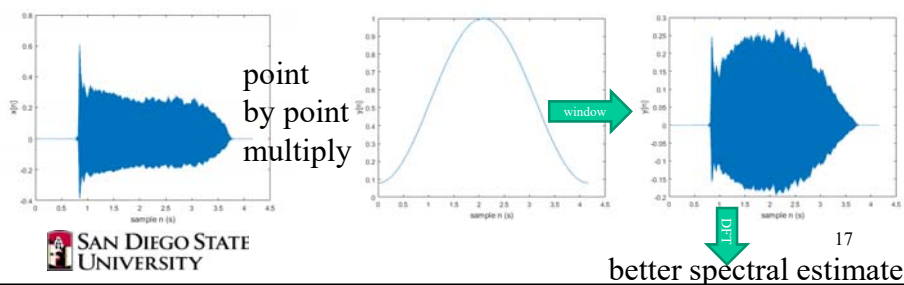
Short-time Fourier Analysis

- By shifting the region where the window is non-zero we can control what portion of the signal remains for each frame.
- We must choose:
 - Frame length
 - Frame advance



Window functions

- Rectangular windows causes energy to “leak” from peaks in the spectrum.
- Reduce effect by tapering edges of window function.



Short-Time Fourier Analysis

- Fourier analysis of the frame m :

$$X_m(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]w_m[n]e^{-j\omega n}$$

- Analysis with discrete frequencies:

$$X_m[k] = \sum_{n=0}^{N-1} x[n]w_m[n]e^{-j2\pi nk/N} \text{ where } 0 \leq k < N$$

frequency associated with bin k in $X_m[k]$ is $\frac{k}{N}Fs$

Python DFT

```
# spyder:
# To avoid tiny inline plots...
# Tools/Preferences/Python Graphics/Backend automatic
# (kernel must be restarted)
import numpy as np
import matplotlib.pyplot as plt

frame_s = 0.020 # frame length
Fs = 8000 # sample rate

frame_N = int(np.round(Fs * frame_s)) # Num samples
tidx = np.arange(frame_N) / Fs # time in s

# sinusoid components for signal
omega = np.array([1000, 2000, 2500]) # frequencies at Hz
amplitudes = np.array([1, .5, .25])
```

Python DFT

```
# build a sine wave
x = np.zeros([frame_N])
for idx in range(len(omega)):
    x = x + (amplitudes[idx] * np.sin(2 * np.pi *
        omega[idx] * tidx))

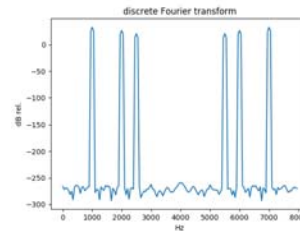
# plot the signal
plt.figure()
plt.plot(tidx, x)
plt.title('Signal')
plt.xlabel('time (s)')
plt.ylabel('Pressure (counts)')
# Use plt.show() if not running ipython
```

Python DFT

```
# Compute discrete Fourier transform
bins_Hz = np.arange(frame_N)/frame_N*Fs
window = signal.get_window("hamming", frame_N)
windowed_x = x * window
X = np.fft.fft(windowed_x)

# spectrum X is complex, convert to dB
magX = np.abs(X)
mag_dB = 20 * np.log10(magX)

plt.figure()
plt.plot(bins_Hz, mag_dB)
plt.title("discrete Fourier transform")
plt.xlabel("Hz")
plt.ylabel('dB rel.')
```



Typical framing parameters

- Window: Hamming.
- Frame/Window length: 20-30 ms.
- Frame advance: 10-20 ms.

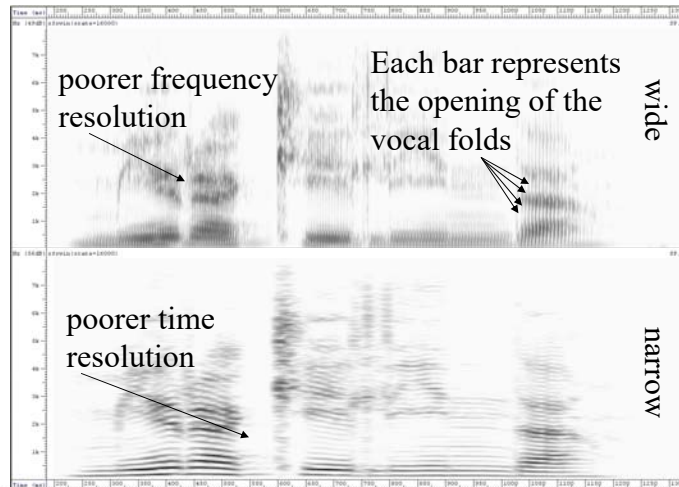
Spectrograms

- Spectrograms are a series of short-time DFTs on windowed segments of a signal
- There are two types of spectrograms:
 - Narrow-band spectrogram
 - Wide-band spectrogram
- The type depends upon the window length.

Window length

- Short ≈ 10 ms or less
 - Better time analysis
 - Frequency bands are widely spaced.
 - F_0 can be estimated by determining time between vertical striations
- Long ≈ 20 ms or more
 - Poor time analysis
 - Frequency bands narrowly spaced.

Narrow vs. Wide-band Spectrogram



Feature vectors

- A set of feature measurements in a D dimensional space
- More is better?

$$\vec{x} = \begin{bmatrix} f_1 \\ f_2 \\ \dots \\ f_{D-1} \\ f_D \end{bmatrix}$$

Feature vectors

- What if f_i and f_j vary in predictable ways?

Then they are not independent: $P(f_i, f_j) \neq P(f_i)P(f_j)$
and their covariance is non-zero

$$\text{cov}(f_i, f_j) = E[(f_i - \mu_{f_i})(f_j - \mu_{f_j})] \neq 0$$

- Strong dependence is not useful



What is the $\text{cov}(f_i, f_i)$?

27

Covariance of features

$$\begin{aligned} \text{cov}(f_i, f_j) &= E[(f_i - \mu_{f_i})(f_j - \mu_{f_j})] \\ &= E[f_i f_j - f_i \mu_{f_j} - \mu_{f_i} f_j + \mu_{f_i} \mu_{f_j}] \quad E[\cdot] \text{ is a linear operator} \\ &= E[f_i f_j] - E[f_i \mu_{f_j}] - E[\mu_{f_i} f_j] + E[\mu_{f_i} \mu_{f_j}] \\ &= E[f_i f_j] - E[f_i] \mu_{f_j} - \mu_{f_i} E[f_j] + \mu_{f_i} \mu_{f_j} \\ &= E[f_i f_j] - \mu_{f_i} \mu_{f_j} - \mu_{f_j} \mu_{f_i} + \mu_{f_i} \mu_{f_j} \\ &= E[f_i f_j] - \mu_{f_i} \mu_{f_j} = \int \int_{f_i f_j} f_i f_j P(f_i, f_j) df_i df_j - \mu_{f_i} \mu_{f_j} \end{aligned}$$

Sample covariance: $\widehat{\text{cov}}(f_i, f_j) = \frac{1}{N-1} \sum_{i=1}^N (f_i - \mu_{f_i})(f_j - \mu_{f_j})$



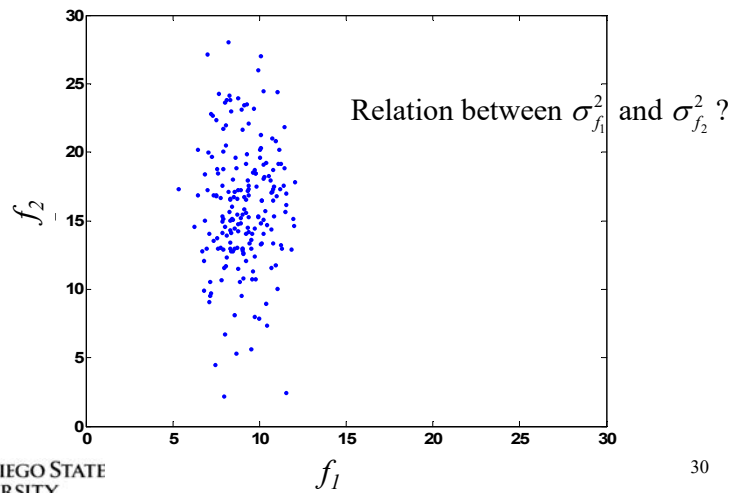
28

Covariance of features

- Ideally, we would like features to be independent.
- Sometimes useful to build a variance-covariance matrix Σ

$$\Sigma = \begin{bmatrix} \text{cov}(f_1, f_1) & \text{cov}(f_2, f_1) & \dots & \text{cov}(f_{D-1}, f_1) & \text{cov}(f_D, f_1) \\ \text{cov}(f_1, f_2) & \text{cov}(f_2, f_2) & \dots & \text{cov}(f_{D-1}, f_2) & \text{cov}(f_D, f_2) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \text{cov}(f_1, f_{D-1}) & \text{cov}(f_2, f_{D-1}) & \dots & \text{cov}(f_{D-1}, f_{D-1}) & \text{cov}(f_D, f_{D-1}) \\ \text{cov}(f_1, f_D) & \text{cov}(f_2, f_D) & \dots & \text{cov}(f_{D-1}, f_D) & \text{cov}(f_D, f_D) \end{bmatrix}$$

Does Σ always make sense?



Correlation matrix R (normalized Σ)

$$R = \begin{bmatrix} \frac{\text{cov}(f_1, f_1)}{\sigma_{f_1} \sigma_{f_1}} & \frac{\text{cov}(f_2, f_1)}{\sigma_{f_2} \sigma_{f_1}} & \frac{\text{cov}(f_{D-1}, f_1)}{\sigma_{f_{D-1}} \sigma_{f_1}} & \frac{\text{cov}(f_D, f_1)}{\sigma_{f_D} \sigma_{f_1}} \\ \frac{\text{cov}(f_1, f_2)}{\sigma_{f_1} \sigma_{f_2}} & \frac{\text{cov}(f_2, f_2)}{\sigma_{f_2} \sigma_{f_2}} & \frac{\text{cov}(f_{D-1}, f_2)}{\sigma_{f_{D-1}} \sigma_{f_2}} & \frac{\text{cov}(f_D, f_2)}{\sigma_{f_D} \sigma_{f_2}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\text{cov}(f_1, f_{D-1})}{\sigma_{f_1} \sigma_{f_{D-1}}} & \frac{\text{cov}(f_2, f_{D-1})}{\sigma_{f_2} \sigma_{f_{D-1}}} & \frac{\text{cov}(f_{D-1}, f_{D-1})}{\sigma_{f_{D-1}} \sigma_{f_{D-1}}} & \frac{\text{cov}(f_D, f_{D-1})}{\sigma_{f_D} \sigma_{f_{D-1}}} \\ \frac{\text{cov}(f_1, f_D)}{\sigma_{f_1} \sigma_{f_D}} & \frac{\text{cov}(f_2, f_D)}{\sigma_{f_2} \sigma_{f_D}} & \frac{\text{cov}(f_{D-1}, f_D)}{\sigma_{f_{D-1}} \sigma_{f_D}} & \frac{\text{cov}(f_D, f_D)}{\sigma_{f_D} \sigma_{f_D}} \end{bmatrix}$$

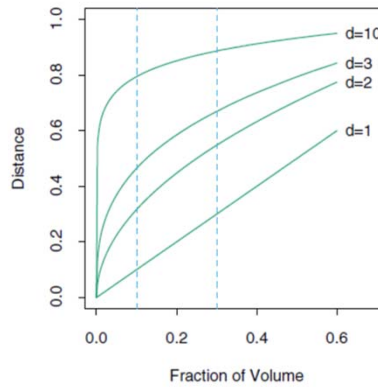
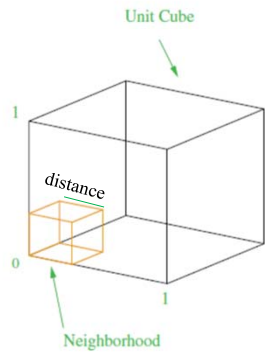
correlation matrix

- Values in $[-1, 1]$
 - Diagonals (R_{ii}) always 1
 - Off-diagonal R_{ij}
 - $> 0 \rightarrow f_i$ and f_j tend to change in same direction
 - $< 0 \rightarrow f_i$ and f_j tend to change in opposite directions
- The closer to -1, 1, the stronger the relationship



Munch's *The Scream*

Curse of dimensionality



Hastie et al. (2009), p. 23

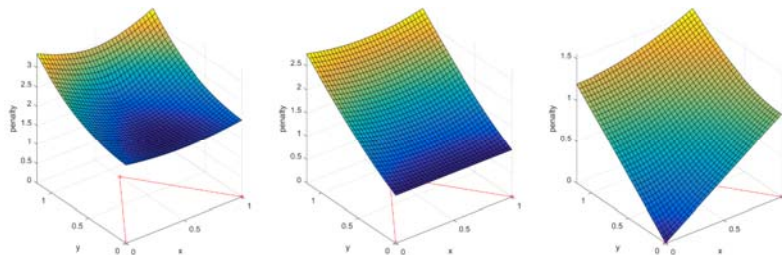
Training features should cover much of the space...



33

Manifolds

- Frequently what we measure can be expressed more compactly.
- Low dimensional representation of higher dimension object



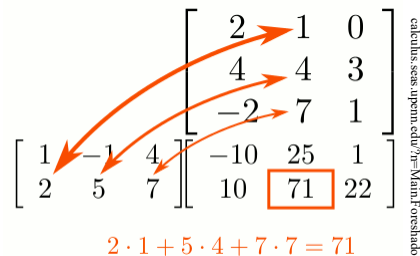
Manifolds

- We'll learn how to do this in a non-linear fashion later in the semester.
- For now, we will use principle components analysis, but we'll need a brief review of linear algebra

Linear algebra review

Goodfellow et al. 2.2 for details

- Matrix multiplication
 - inner dimension must match:
 $[2 \times 3][3 \times 3] = [2 \times 3]$


$$\begin{bmatrix} 1 & 2 & -1 \\ 2 & 5 & 7 \end{bmatrix} \begin{bmatrix} 4 & 10 & 7 \\ -2 & 7 & 1 \\ -10 & 25 & 1 \end{bmatrix} = \begin{bmatrix} 10 & 22 & 71 \\ 2 & 5 & 7 \end{bmatrix}$$

$2 \cdot 1 + 5 \cdot 4 + 7 \cdot 7 = 71$

calculus.secs.upenn.edu/~manf/overshadowing

Eigen vectors

Goodfellow et al. 2.7 for details

- Special vectors such that in

$$Ax = b$$

$$\lambda x = b \text{ for some } \lambda \in \mathfrak{R}$$

- These are the directions in which the matrix merely scales vectors.
- Directions are uncorrelated.
- When the vector is a unit vector, the scale factor is the eigen value.

Principal components analysis (PCA)

- Finds new basis set to represent data
- Relies on eigen vectors and values
- Bases account for different amounts of variance in data and low contributors can be discarded



PCA – Let's get our hands dirty



USFWSmidwest CC 2.0

- Let X be an $N \times D$ data matrix
- Assume expected value has been subtracted (no loss of generality)
- Can think of feature space as
 - having basis vectors u_1, u_2, \dots, u_D along axes
 - each row of X is a combination of those vectors

PCA

- Goal: Pick a new set of basis vectors
 - First vector

$$X \begin{bmatrix} w_{(1),1} \\ w_{(1),2} \\ \vdots \\ w_{(1),D} \end{bmatrix} = y \quad \text{produces vector of } y \text{ values in direction } w_{(1)}$$

- Select such that $\text{var}(y)$ is maximized subject to

$$\sum_{i=1}^D w_{(1),i}^2 = 1$$

- Repeat finding next largest uncorrelated basis

PCA

- In practice, this becomes an eigenvector problem on the variance-covariance matrix
- Principal components are eigenvectors ordered by descending eigenvalue.

Computing PCA

- Estimate covariance matrix Σ of X
 X is an $N \times D$ data matrix
- Compute eigen vectors e_i and values λ_i of Σ
and arrange by largest eigen value to
smallest:

$$e_1, e_2, \dots, e_D$$

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_D$$

Using PCA

- To project data, multiply by the number of bases desired, e.g. for data matrix X

$$\begin{array}{c}
 \begin{bmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,D} \\ x_{2,1} & x_{2,2} & \dots & x_{2,D} \\ \dots & \dots & \dots & \dots \\ x_{N-1,1} & x_{N-1,2} & \dots & x_{N-1,D} \\ x_{N,1} & x_{N,2} & \dots & x_{N,D} \end{bmatrix} \\
 \text{NxD}
 \end{array}
 \begin{array}{c}
 \begin{bmatrix} e_{1,1} & \dots & e_{m,1} \\ \vdots & & \vdots \\ e_{1,D} & & e_{m,D} \end{bmatrix} \\
 \text{Dxm}
 \end{array}
 =
 \begin{array}{c}
 \begin{bmatrix} b_{1,1} & b_{1,2} & \dots & b_{1,m} \\ b_{2,1} & b_{2,2} & \dots & b_{2,m} \\ \dots & \dots & \dots & \dots \\ b_{N-1,1} & b_{N-1,2} & \dots & b_{N-1,m} \\ b_{N,1} & b_{N,2} & \dots & b_{N,m} \end{bmatrix} \\
 \text{Nxm}
 \end{array}$$

$1 \leq m \leq D$
 project to m dimensions



Use [numpy.dot](#) to multiply matrices

43

How much of the variance is captured?

- $\sum (tr(\Sigma)) = \sum_{i=1}^D \lambda_i$ Sum of variances (sum of trace) is the same as the sum of the eigen values
- The first m dimensions contain the variance represented by the sum of their eigen

values:

$$\frac{\sum_{i=1}^m \lambda_i}{\sum_{j=1}^D \lambda_j}$$



44

Component loadings

Loadings give the correlation between the bases and the features, e.g. for eigen vector e_i :

$$\frac{e_{i,1}\sqrt{\lambda_i}}{\sigma_{f_1}} \quad \frac{e_{i,2}\sqrt{\lambda_i}}{\sigma_{f_2}} \quad \dots \quad \frac{e_{i,D-1}\sqrt{\lambda_i}}{\sigma_{f_{D-1}}} \quad \frac{e_{i,D}\sqrt{\lambda_i}}{\sigma_{f_D}}$$

PCA of correlation matrix

- The same analysis can be done on the sample correlation matrix R
- Eigen values will add up to D . Why?
- What is the qualitative difference with this type of analysis?